

$$(6.404) \quad \psi_{k\pm}^{1/2} \sim |\pm 1/2\rangle_k \sim \tilde{r}(\rho) \odot_k e^{\pm i_k 1/2 \phi_k} \sim \text{(simplified as)} \quad \widehat{\psi}_{k\pm}^{1/2} \sim e^{\pm i_k 1/2 \phi_k} \in \mathbb{H}.^{358}$$

Each with specified i_k **directions**, and all three acting together simultaneously.

These are endowed with angular momentum eigenvalue bivectors $L_k^\pm = \pm 1/2 \hbar i_k = \pm 1/2 \hbar i \sigma_k$

The equivalent rotors $U = e^{1/2 i b} \sim e^{i_k 1/2 \phi_k}$ possess the transversal plane normal-axial cylinder symmetry around the 1-vector b . This we know from the regular rotation (6.70) that acts on an arbitrary geometric (multi)-vector x by canonical sandwiching by the rotor and its reversed

$$(6.405) \quad \underline{R}x = UxU^\dagger = e^{1/2 i b} x e^{-1/2 i b} = e^{i b} x$$

Whence we instead of the subton stats (6.402) in these **directions** use the rotor stats (6.404)

$$(6.406) \quad U = e^{+1/2 i b} \rightarrow \widehat{\psi}_{k\pm}^{1/2} = e^{\pm i_k 1/2 \phi_k},$$

as templet proportional to the spinor states for each $k = 1, 2, 3$, with the symmetries $\odot_k = e^{i_k \theta}$

$$(6.407) \quad \psi_{k\pm}^{1/2}(\rho) = \tilde{r}(\rho) \odot_k e^{\pm i_k 1/2 \phi_k}, \text{ for } \forall \rho \geq 0, \quad \text{where } \int_0^\infty \psi_{k\pm}^{1/2} \psi_{k\pm}^{1/2} d\rho = \langle \psi_{k\pm}^{1/2} | \psi_{k\pm}^{1/2} \rangle = \frac{1}{4}.$$

We have three such components of orthogonal oscillating spinor states endowing angular momenta. We remember that these states do not commute as described in § 6.3.5.2, therefor their individual independent **directions** σ_k cannot be reduced. (Their interconnectivity does the impact.)

They exist in the planes of the exponential functions $e^{\pm i_k \phi_k}$, that is the plane supported by the unit argument **direction** indicated by i_k , which is the free eigen-planes of $L_k^\pm = \pm \hbar i_k = \pm \hbar i \sigma_k$.

For simplicity, we remove the distribution factor $\tilde{r}(\rho) \odot_k$ and replace it with the amplitude ρ_k

$$(6.408) \quad \psi_{k\pm}^{1/2} = \rho_k e^{\pm i_k 1/2 \phi_k} = \rho_k (\cos 1/2 \phi_k \pm i_k \sin 1/2 \phi_k) \in \mathbb{H}, \quad \text{as (6.164)-(6.166).}$$

These three $\mathcal{G}_{0,2}(\mathbb{R})$ multivector state components can be linear combined for a full **entity** $\Psi_{1/2}$

$$(6.409) \quad \psi_\pm^{1/2} = \psi_{3\pm}^{1/2} + \psi_{2\pm}^{1/2} + \psi_{1\pm}^{1/2} \in \mathbb{H}.$$

Special for the external chosen **direction** $i_3 = i \sigma_3$, we change $\rho = \rho_3$ and $\phi = \phi_3$ (see (6.146))

$$(6.410) \quad \psi_{3+}^{1/2} = \rho_3 e^{+i_3 1/2 \phi_3} = \rho (\cos 1/2 \phi + i_3 \sin 1/2 \phi) \in \mathbb{H}.$$

For the other **directions**, we left multiply operate this by a quaternion spinor factor $\frac{1}{2} \frac{\rho}{\rho} i_2 e^{i_3 1/2 \theta}$

$$(6.411) \quad \frac{\rho}{2\rho} i_2 \odot_3 \psi_{3+}^{1/2} \sim \psi_{2+}^{1/2} = \frac{1}{2} \rho (i_2 \cos 1/2 \psi + i_1 \sin 1/2 \psi), \quad \text{with } \psi = \phi + \theta.$$

or operate (6.410) by the factor $\pm \frac{\rho}{2\rho} i_1 e^{i_3 1/2 (\theta \mp \pi)}$ and using e.g., $\pm \psi_1 = \psi \mp \pi \leftarrow \phi + \theta$.

$$(6.412) \quad \pm \frac{\rho}{2\rho} i_1 \odot_3 \psi_{3+}^{1/2} \sim \psi_{1\pm}^{1/2} = \pm \frac{1}{2} \rho (i_1 \cos 1/2 \psi_1 - i_2 \sin 1/2 \psi_1) = \frac{1}{2} \rho (i_1 \sin 1/2 \psi + i_2 \cos 1/2 \psi).$$

Here we now use ρ as a real amplitude factor.³⁵⁹ We note the phase orientation for $\pm \frac{1}{2} i_1$.

These two (6.411)-0 are the same, whereby we can remove the factor $\frac{1}{2}$ and get

$$(6.413) \quad \psi_{1+}^{1/2} = \psi_{2+}^{1/2} + \psi_{1+}^{1/2} = \rho (i_2 \cos 1/2 \psi + i_1 \sin 1/2 \psi) = \rho i_{\perp} (1/2 \psi),$$

as a spinning bivector oscillation shown in Figure 6.16 in agreement with the impact of the interconnectivity expressed in (6.151)-(6.155). The independency $\phi \neq \psi$ is a phase factor θ .

We note a **quality**, a phase shift 2π in e.g. ψ_1 change the orientation of that contribution $\psi_{1\pm}^{1/2}$.

6.5.8.3. The Oscillator Fluctuating Versor Wavefunction for the Entity $\Psi_{1/2}$ in 3 space

The superposition of these by (6.409) gives the quaternion (see § 6.4.4.3)

$$(6.414) \quad \psi_{\pm 1/2} = \psi_{3\pm}^{1/2} + \psi_{2\pm}^{1/2} + \psi_{1\pm}^{1/2} = \rho (\cos 1/2 \phi + i_3 \sin 1/2 \phi) + \rho (i_2 \cos 1/2 \psi + i_1 \sin 1/2 \psi) \\ \sim U = \hat{Q} = u_0 + u_3 i_3 + u_1 i_1 + u_2 i_2 \in \mathbb{H} \sim \mathcal{G}_{0,2}(\mathbb{R}).$$

This we compare to (6.168) using the definitions (6.145f)-(6.150) and find that the versor quaternion is fully capable to describe an **entity** $\Psi_{1/2}$ in 3-space.

³⁵⁸ The double k index $i_k \phi_k$ in the exponent is not summed here in this § when we are looking at the components. This is due to the causal sequential product operations do not commute.

³⁵⁹ Here not as a polar coordinate for density distribution $\tilde{r}(\rho)$ in physical space. The replacement is rather $\rho \leftarrow \langle \tilde{r}(\rho) \rangle$.

This quaternion 2-rotor is unitary if (6.150) is fulfilled $\rho^2 + \rho^2 = u_0^2 + u_3^2 + u_1^2 + u_2^2 = 1$

We also see that a free oscillating versor quaternion is governed by two angular development parameters, e.g. given as (6.148)-(6.149) performing 1-spinor oscillations (6.146)-(6.147)

$$(6.415) \quad Q_3 = (u_0 + u_3 i_3) = \rho e^{+i_3 1/2 \phi} \in \mathbb{H} \quad \leftrightarrow \quad \alpha = z_3 = \rho e^{+i_3 1/2 \phi} \in \mathbb{C}, \quad \text{as (6.170),}$$

$$(6.416) \quad Q_1 = (u_2 - u_1 i_3) = \rho e^{-i_3 1/2 \psi} \in \mathbb{H} \quad \leftrightarrow \quad \beta = z_1 = \rho e^{-i_3 1/2 \psi} \in \mathbb{C}, \quad \text{as (6.171).}$$

The condition (6.150) fulfil a 4-dimensional \mathbb{R}^4 unit sphere with S^3 symmetry

$$(6.417) \quad S^3 = \{ \forall (u_0, u_1, u_2, u_3) \in \mathbb{R}^4 \mid u_0^2 + u_1^2 + u_2^2 + u_3^2 = 1 \} = \{ \forall (z_1, z_3) \in \mathbb{C}^2 \mid |z_1|^2 + |z_3|^2 = 1 \} = \{ \forall \hat{Q} \in \mathbb{H} \mid |\hat{Q}| = 1 \}.$$

This abstract S^3 -spherical symmetry of 3-space is the fundament for the isomorphic structure of the versor-quaternion group of the geometric algebra, the lifted Pauli group, and the 2×2 complex matrix group $SU(2)$ (6.175) in a way that its elements possess the **primary quality** of a **free entity** $\Psi_{1/2}$ in 3-space.

All the possible traditional two angular **spherical coordinates** $(1, \theta, \varphi)$, the polar angle θ , and the azimuthal angle φ describe all **directions** in a unit sphere. For completeness, we include a third quantum mechanics phase angle from $\odot \leftrightarrow U(1)$ for the overall symmetry consideration.

The total spherical symmetry is broken by an external field possessing angular momentum creating a conical precession of angular momentum of an **entity** $\Psi_{1/2}$ interpreted from the external as displayed in Figure 6.22. This field can be established by an inhomogeneous magnetic field as in the Stern-Gerlach experiment. The field gradient with a lab frame **direction** $\sigma_3 = e_3$ consist of free subtons $\psi_{3\pm} \sim e^{\pm i_3 \omega_s t}$ (6.402)³⁶⁰, that possess angular momentum $L_3^\pm = \pm \hbar i_3 = \pm \hbar i \sigma_3$, with magnitude **quantum** $\hbar 1$, that interact as the symmetry braking mechanism.

Here the exchange **quantum** is the subton Ψ_{ω_s} frequency energy $\hbar \omega_s$ as kinetic energy with the line momentum $(\hbar/c) \omega_s$ of one subton delivered *to* or *from* each **entity** $\Psi_{1/2}$.

The amount $\hbar \omega_s$ absorbed in or emitted from $\Psi_{1/2}$ by the subton is reasonably small compared to the internal oscillation energy (“mass”) of $\Psi_{1/2}$, making it move *up* or *down* along the gradient³⁶¹ $b(x_3) e_3$ in the e_3 **direction** of the inhomogeneous magnetic field as a transversal plane bivector $b(x_3) i e_3$ in the experiment. Then the total angular momentum of $\Psi_{1/2}$ must be aligned to do a precession around $\sigma_3 = e_3$ along $i e_3$ with the projection on this $L_3^{w_s} = \pm \frac{1}{2} \hbar i_3 = \pm \frac{1}{2} \hbar i e_3$.

The thought is that the first interaction with each $\Psi_{1/2}$ aligned spin $1/2$ parallel or antiparallel to the gradient randomly from the prerequisite **direction** of $\Psi_{1/2}$. Then the gradient **direction** locks the orientation of $L_3^{w_s}$ to $+\frac{1}{2} \hbar i e_3$ or $-\frac{1}{2} \hbar i e_3$. Further interaction with the magnetic field is then a polarized acceleration.

The S^3 -spherical symmetry is broken to an intuitive conical **lab** average shown in Figure 6.22.

The reader should compare this to (6.218)-(6.219), (6.223) considering the autonomous magnitude factor $|j_\pm^{w_s}| = \sqrt{3/4} |n|$ and note (6.140)

$$(6.418) \quad n := (u_1 \sigma_1 + u_2 \sigma_2 + u_3 \sigma_3) / \sqrt{1 - u_0^2} = n_1 \sigma_1 + n_2 \sigma_2 + n_3 \sigma_3, \quad \text{where } |n| = 1,$$

and compare with the S^2 spherical symmetry

$$(6.419) \quad S^2 = \{ \forall (n_1, n_2, n_3) \in \mathbb{R}^3 \mid n_1^2 + n_2^2 + n_3^2 = 1 \},$$

where the **direction** symmetry is broken by the projection (6.379), (6.388) $j_3 \rightarrow j_3^{w_s} = \pm \frac{1}{2} \hbar \sigma_3$, that we interpreted from the external frame $\{e_1, e_2, e_3\}$ where $\sigma_3 = e_3$, therefor we write

$$(6.420) \quad j_3^{w_s} = \pm \frac{1}{2} \hbar e_3. \quad ^{362}$$

³⁶⁰ The thought experiment here is, that the static magnetic gradient consists of up subtons $e^{+i_3 \omega_s t}$ and down subtons $e^{-i_3 \omega_s t}$, which as energy flow balance each other but give a resulting angular momentum, that can interact with our **entity** $\Psi_{1/2}$.

³⁶¹ We use a real scalar function $b(x_3) \in \mathbb{R}$ as a coefficient to the **direction** e_3 to describe the gradient field along the coordinate x_3 .

³⁶² Remember that the unit of e_3 must be one $|e_3| = 1 = \hbar$ in a **quantum** unit system. In other systems, e_3 can have the unit $[\hbar^{-1}]$.