- II. . The Geometry of Physics – 5. The Geometric Plane Concept – 5.7. Plane Concept Idea of a Non-Euclidean Clifford

The decrease in the received oscillating frequency energy dilates the chronometric count along the locally defined development parameter relative to the local equivalent identical *entity* $\Psi_{\rm R}$, $[\omega_0^{-1}]$.

5.7.4.5. The Space-Time Algebra STA from a 4-dimensional 1-vector basis

Often the Minkowski \mathcal{B} -plane is called the Lorentz plane because it is the hyperbolic plane for the Lorentz rotation. What happens externally outside this plane? The tradition is to make a time dimension and three space dimensions with opposite signatures, we use in this book (+, -, -, -)for a Clifford algebra $\mathcal{G}_{1,3}(\mathbb{R})$ the Minkowski metric space foundation basis $\{\gamma_0, \gamma_1, \gamma_2, \gamma_3\}$.

The *direction* γ_0 is the unit cyclic measure of development, which is an isometric measure for the three-dimensional *directions* units $\gamma_1, \gamma_2, \gamma_3$ of Descartes extension: *length*, *breadth*, *depth* in the so-called natural space. The STA basis $\{\gamma_0, \gamma_1, \gamma_2, \gamma_3\}$ we define as orthonormal, from (5.300)-(5.304) we have

(5.377)

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 $\gamma_0 \cdot \gamma_1 = \gamma_0 \cdot \gamma_2 = \gamma_0 \cdot \gamma_3 = 0, \ |\gamma_0| = |\gamma_1| = |\gamma_2| = |\gamma_3| = 1,$ $\gamma_1 \cdot \gamma_2 = \gamma_2 \cdot \gamma_3 = \gamma_3 \cdot \gamma_1 = 0. \leftarrow \text{Orthogonal extensions, therefor } \bot.$

As we have seen above $\gamma_0 \cdot \gamma_k = 0$ are in substance not perpendicular, in that their *directions* can be changed by a Lorentz rotation. Anyway, we display the γ_0 *direction* as perpendicular to all NOW lines in Figure 5.56the NOW plane $\gamma_1 \gamma_2$ of , where $\gamma_0 || (\gamma_1 \gamma_2)$. The three extension *direction* unit 1-vectors γ_k display a three dimensional Cartesian basis, that local is both perpendicular and orthonormal. The development dimension is not spatial, and therefore we display the *direction* unit γ_0 as cyclic oscillating around in a unit circle following the arc of its circumference repeating itself periodically for every $2\pi\gamma_0$ The founding unit γ_0 reference is then the radian measure of the unit circle performing an oscillation with an autonomous frequency energy ω of the local *entity*. The oscillating rotation is then performed by $e^{\gamma_2 \gamma_1 \omega t}$, traditional prescribed $e^{-i\omega t} \in \mathbb{C}$, where t is the development chronometer. The reader is encouraged to compare this chronometric timing concept with Figure 1.2 in chapter I. 1.6.2.3. When it comes to the impact on extension space compare it with the idea of Figure 3.13 in chapter I. 3.4.1.

Interpreted as a tangent 1-vector, γ_0 support a classical (Augustinian) timeline going from the first beginning to the final end $(A \rightarrow \Omega)$. Herein this book we (similar to the ancient Greeks) like to wrap this concept into an oscillating circular rotation for each local autonomous defining *entity*. When it comes to two *entities* Ψ_A and Ψ_B separated in the extension *direction* γ_3 where Ψ_B gets information about Ψ_A , we need a third signal entity Ψ bringing the information about Ψ_A to Ψ_B . We set the speed of this subton Ψ to one unit $\beta = 1$ (e.g., speed of light c=1) observed from both Ψ_A and Ψ_B . Seen from Ψ_B the transmission *direction* of the signal Ψ will fall in the *null direction* of the receiving *entity* $\Psi_{\rm B}$ that is the interpreting observer.

In principle Figure 5.55 show the same situation as Figure 5.56 for a subton Ψ intuits from external for the receiving situation at B, the difference are in the interpretations of the displays.

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Geometric Research Critique on th of Pure $\overline{\mathbf{O}}$ 2 priori Mathematical Reasoning of Figure 5.56 The STA basis $\{\gamma_0, \gamma_1, \gamma_2, \gamma_3\}$ Phys10 displayed as perpendicular directions in all four dimensions. We chose the γ_3 *direction* for the relativistic velocity that causes the Lorentz Ô rotation $e^{\gamma_3 \gamma_0 \zeta}$ in a **U** Minkowski **B**₂-plane direction $\mathcal{B}_3 \equiv \gamma_3 \gamma_0$ that is not displayed. The Euler oscillating rotation $e^{\gamma_2 \gamma_1 \omega t}$ by the arc *direction* γ_0 in the extension plane sup-en ditio ported by $\gamma_1 \gamma_2 = \mathbf{i}_3$. The *null direction* is shown as *null helixes* Ś collapsed around the γ_2 1 \mathbf{I} extension *direction*. N rfurt Undecided orientation $-\mathcal{B}_k = \gamma_0 \gamma_k$ or $\mathcal{B}_k = \gamma_k \gamma_0$ \bigcirc N 020-22 Andres

0

null helix

5.7.5. The planes of Space-Time Algebra and the Euclidean Cartesian plane

- 5.7.5.1. Founding Summary of Minkowski Space with Euler and Lorentz Rotations In this section 5.7 we have introduced the Minkowski metric space as a Clifford algebra with mixed signatures, (+) for development and (-) for extensions, by defining a Minkowski \mathcal{B} -plane bivector in § 5.7.1 with signatures (+, -) for the algebra $\mathcal{G}_{1,1}(\mathbb{R})$ and introducing *null directions* for information, and in § 5.7.1.3, the development count γ_0 as an isometric measure. The traditional Minkowski display is interpreted in section 5.7.2, first for the plane display (+, -) in Figure 5.53, then in § 5.7.2.2 this plane display is Euler rotated around in a two-dimensional extension plane $\gamma_1 \gamma_2$ direction resulting in a Minkowski space algebra $\mathcal{G}_{1,2}(\mathbb{R})$ with signature (+, -, -) displayed in Figure 5.54, with a *null* cone. In §5.7.2.3 this is supplementerted with a third dimension of extension γ_3 , forming the full STA Minkowski signature (+, -, -, -). From the paravector concept p in section 5.7.3 we get from the development count γ_0 the STA Clifford algebra $\mathcal{G}_{1,3}(\mathbb{R})$ with its 1-vector concept $p = p\gamma_0$ (5.345). The Lorentz rotation is discussed in section 5.7.4 as a hyperbolic rotation in a \mathcal{B} -bivector-plane, then as a Lorentz transformation § 5.7.4.2 of the paravector, and the STA Lorentz boost in § 5.7.4.3 with the relativistic speed β , and invariant quantities of information with a hyperbolic same folding of development to a helix extension *directions* approaching the *null direction* for $\beta \rightarrow 1$.
- 5.7.5.2. Mapping Operation Between STA planes and the Euclidean Cartesian plane As the ideological foundation for the plane concept, we choose to use the Euclidean approach by the Cartesian orthonormal basis $\{\sigma_1, \sigma_2\}$ that we immediately expand to the standard basis (5.198) $\{1, \sigma_1, \sigma_2, i \coloneqq \sigma_2 \sigma_1\}$ for the Euclidean plane algebra. Our experience has taught us, that is an oversimplified static view, where nothing happens, and no information is transmitted. Any knowledge of the physical situation in this is a priori transcendental to our intuition, as Immanuel Kant told us. We must endow the situation with a measuring concept, which makes something happens. We need a reference for this, and this is a cyclic oscillator with a stable reliable angular frequency energy ω , which makes the *one quantum* count for us. This oscillator possesses an information development *direction* unit γ_0 . We expand the sequential order of counts to a real number continuous monotone growing parameter span of development *direction* $\{\lambda_0\gamma_0 | \forall \lambda_0 \in \mathbb{R}, \gamma_0^2 \coloneqq 1 \in \mathbb{R}\}$ as a linear Euclidean algebra $\mathcal{G}_1(\mathbb{R})$ of one dimension for a continuous 1-vector concept $\lambda_0 \gamma_0$ of a *development direction*, a primary quality of first grade (pgg-1), that indeed not possess any Descartes extension in space. We choose this continuous count to be the measure for the Euclidean plane object defined by the Cartesian orthonormal basis { $\sigma_1^2 = \sigma_2^2 = 1$, σ_1, σ_2 }. Measure $\gamma_0^2 \approx 1$ is the measure for these two $\sigma_1^2 = \sigma_2^2 = 1$. The information signal generated from the oscillating generator for γ_0 must be isometric for both σ_1 and σ_2 transmitted from their common bottom to their tips; vice versa. The measurement mapping is established by the multiplication operation (5.328): {1, σ_1 , σ_2 } γ_0 (5.378) $\{1\gamma_0, \boldsymbol{\sigma}_1\gamma_0, \boldsymbol{\sigma}_2\gamma_0\} = \{\gamma_0, \gamma_1, \gamma_2\}.$ Then we have an autonomous isometric orthonormal basis for a plane in STA. We remember the negative signature for $\gamma_1^2 = \gamma_2^2 = -1$, confirmed by $\sigma_k \gamma_0 \sigma_k \gamma_0 = -\sigma_k \sigma_k = -\sigma_k^2$. The Euclidean plane unit bivector $\mathbf{i} = \mathbf{\sigma}_2 \mathbf{\sigma}_1$ is mapped by $\gamma_0^2 = 1$ $\mathbf{i} = \mathbf{i}\gamma_0^2 = -\mathbf{\sigma}_2\gamma_0\mathbf{\sigma}_1\gamma_0 = -\gamma_2\gamma_1 = \gamma_1\gamma_2.$ Now we have done the map for the Euclidean plane concept represented by their standard bases (5.379) $\{1, \boldsymbol{\sigma}_1, \boldsymbol{\sigma}_2, \boldsymbol{i} \coloneqq \boldsymbol{\sigma}_2 \boldsymbol{\sigma}_1\} \leftrightarrow \{\gamma_0, \gamma_1, \gamma_2, \gamma_1 \gamma_2\}$ (5.380)

and connected the extension in the Cartesian plane with an oscillating reference measure γ_0 . Then we have the isometric measure in what David Hestenes call Space-Time-Algebra (STA) [6]

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- 5.7.5. The planes of Space-Time Algebra and the Euclidean Cartesian plane - 5.7.5.2 Mapping Operation Between STA