Geometric

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#### - II. The Geometry of Physics – 5. The Geometric Plane Concept – 5.2. The Plane Geometric Algebra –

This leads to, that the area segment of a subject bivector **B** in principle is a *pseudoscalar*<sup>220</sup> for the plane, even though the object  $\mathbf{b} \perp \mathbf{a}$  rectangle has a scalar area magnitude

#### $|\mathbf{B}| = |\mathbf{b}||\mathbf{a}| \in \mathbb{R}_+ \geq 0.$ (5.67)

We say that the unit bivector  $\hat{\mathbf{B}}$  is the *unit pseudoscalar* for that plane it defines.

### 5.2.5.4. A Bivector Multiplied by a 1-vector

First, a bivector is defined as its resolution of two 1-vectors  $\mathbf{B}=\mathbf{b}\wedge\mathbf{a}$ , that in the tradition span the plane concept substance. In that plane, an outer product of three 1-vectors vanish  $\mathbf{b} \wedge \mathbf{a} \wedge \mathbf{c} = 0$ . Therefor  $\mathbf{B} \wedge \mathbf{c} = \mathbf{0}$  express that any relevant 1-vector **c** is internal in the plane spanned by **B**.<sup>221</sup>

A bivector **B** anticommute in multiplying by any each 1-vector in its plane

#### $\mathbf{B}\mathbf{a} = -\mathbf{a}\mathbf{B}$ (5.68)

the reason is, there exist a **b** using (5.66)  $\exists \mathbf{b} \cdot \mathbf{a} = 0 \Rightarrow \mathbf{B} = \mathbf{b}\mathbf{a} \Rightarrow \mathbf{B}\mathbf{a} = \mathbf{b}\mathbf{a}\mathbf{a} = -\mathbf{a}\mathbf{b}\mathbf{a} = -\mathbf{a}\mathbf{B}$ . This product in a plane is a 1-vector **Ba** =  $ba^2 \Rightarrow b = Ba/a^2$ The multiplicative inverse 1-vector from (4.76)

$$(5.69) a^{-1} = \left(\frac{1}{a}\right) = \frac{a}{a^2}$$

makes it possible to *divide* with a 1-vector in the same plane.

(5.70) 
$$Ba^{-1} = -a^{-1}B$$

or rather multiplying by the inverse 1-vector from the right or left is anti-commuting.<sup>222</sup>

#### 5.2.5.5. The Category a Bivector

We conclude the fundamental *category* for the conceptual bivector idea: Bivectors may be the same or different. An individual bivector can be divided into several bivectors, and different bivectors can be combined into one bivector. A bivector quality we give by a *direction* unity-plane-segment bivector  $\hat{\mathbf{B}}$  by def. (5.65) applied to (5.66), hence

$$\widehat{\mathbf{B}}^2 = -\left|\widehat{\mathbf{B}}\right|^2 =$$

The squared normalized *quantity* of a plane-segment *direction*  $\hat{\mathbf{B}}$  is then  $-1 \in \mathbb{R}^{1}_{pag-2}$ . The bivector *quantity* is simply performed by  $\mathbf{B} = \beta \hat{\mathbf{B}}$  for  $\forall \beta \in \mathbb{R}^{1}_{\text{pag-2}}$ .

This factor  $\beta$  span a plane from  $\hat{\mathbf{B}}$ .

Bivectors have existence or not by multiplication of 1-vectors in

two important particular cases of possible existing 1-vectors:

Orthogonal 1-vectors anticommute  $\mathbf{b} \cdot \mathbf{a} = 0 \Leftrightarrow \mathbf{b} \mathbf{a} = -\mathbf{a} \mathbf{b}, |\cos \theta = 0|$ *Collinear* 1-vectors commute  $\mathbf{a} = \lambda \mathbf{b} \Leftrightarrow \mathbf{b} \wedge \mathbf{a} = \mathbf{0} \Leftrightarrow \mathbf{b} \mathbf{a} = \mathbf{a} \mathbf{b}$ ,  $\sin \theta = \mathbf{0}$ a 1-vector **a** is colinear with itself, so  $\mathbf{a} \wedge \mathbf{a} = 0$ , for  $\forall \mathbf{a}$ , as well  $\mathbf{a} \cdot \mathbf{a} = \mathbf{a}^2$ 

Two *colinear* 1-vectors do not constitute a bivector.

Two orthogonal 1-vectors constitute a wedge product for a plane rectangular area.

<sup>220</sup> I	n Geometric Algebra (Clifford Algebra) the pseudoscalars are the highest grade elements in the primary quality grades that a
t	necessary for the algebra. Euclidian pseudoscalars square to a negative scalar and commute with all even elements.
<sup>221</sup> A	A third 1-vector <b>c</b> will give impact $b \land a \land c \neq 0$ when it is exterior to the plane $b \land a$ . (see later below chapter 6).
222 -	$\mathbf{r}_1$ $\mathbf{r}_2$ $\mathbf{r}_3$ $\mathbf{r}_4$ $\mathbf{R}_1$ $\mathbf{r}_2$ $\mathbf{r}_3$ $\mathbf{r}_4$ $\mathbf$

The division symbol  $\frac{\mathbf{n}}{2}$  makes no sense! But multiplication by the inverse 1-vector  $\mathbf{a}^{-1} = \frac{1}{\mathbf{a}}$  from the right or the left is allowed.

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## -5.2.6. The Orthonormal Bivector Object as a Unit for the Circular Rotation in a Plane -5.2.6.3 Operations with the Unit

#### 5.2.6. The Orthonormal Bivector Object as a Unit for the Circular Rotation in a Plane We look at the orthogonal unit vectors $\sigma_1$ and $\sigma_2$ also called an orthonormal basis $\{\sigma_1, \sigma_2\}$ for a plane. – By definition, it applies a priori: Orthogonal: $\mathbf{\sigma}_1 \cdot \mathbf{\sigma}_2 = 0$ and Normalised: $\mathbf{\sigma}_1^2 = \mathbf{\sigma}_2^2 = 1 \Rightarrow |\mathbf{\sigma}_1| = |\mathbf{\sigma}_2| = 1$ . From here we form a bivector for the plane that we call $\mathbf{i} \coloneqq \mathbf{\sigma}_2 \wedge \mathbf{\sigma}_1$ Since $\sigma_2 \cdot \sigma_1 = 0$ , for this bivector we have (5.72)as just the product of the two orthonormal basis vectors for the plane and by antisymmetric permutation, we have the two orientations<sup>223</sup> (5. $\sigma_2$ Which means that $\mathbf{i}$ is the special multivector constituted by one bivector. According to $|\mathbf{\sigma}_1| = |\mathbf{\sigma}_2| = 1$ in (5.66) and $\mathbf{\sigma}_2 \cdot \mathbf{\sigma}_1 = 0 \Rightarrow \sin^2 \theta = 1$ in (5.62), together with (5.71) we have the auto product (5 This leads to the normalized magnitude of $|\mathbf{i}| = |-\mathbf{i}| = 1$ Therefore, both $\mathbf{i}$ and $-\mathbf{i}$ are the two unitary bivectors. Figure 5.12 Unit 2-blade The unit for the *direction* of a plane segment $\hat{\mathbf{B}}$ has two eigenstates $\mathbf{i} = \mathbf{\sigma}_2 \mathbf{\sigma}_1$ or $-\mathbf{i} = \mathbf{\sigma}_1 \mathbf{\sigma}_2$ and $\pm \pi/2$ rotation objects. $-\left|\widehat{\mathbf{B}}\right|^2 = -1$ (5.7

2) 
$$\mathbf{i} = \mathbf{\sigma}_2 \wedge \mathbf{\sigma}_1 = \frac{1}{2} (\mathbf{\sigma}_2 \mathbf{\sigma}_1 - \mathbf{\sigma}_1 \mathbf{\sigma}_2) = \mathbf{\sigma}_2 \mathbf{\sigma}_1$$

(4.73) 
$$\boldsymbol{i} \coloneqq \boldsymbol{\sigma}_2 \boldsymbol{\sigma}_1$$
 with the commuted  $-\boldsymbol{i} = \boldsymbol{\sigma}_1$ 

5.74) 
$$ii = i^2 = -1$$
.

75) 
$$\hat{\mathbf{B}} = \pm i = \pm 1i$$
, in that  $\hat{\mathbf{B}}^2 = i^2 = -|i|^2 =$ 

We say that the unit-plane-segment *direction*  $\hat{\mathbf{B}}$  has two eigenvalues 1 and -1. Compared with quantum mechanics we intuit **i** as a *direction operator* for a unit-area-segment. Any arbitrary plane area  $\beta = |\mathbf{B}| \ge 0$  provided by a bivector  $\mathbf{B} = \beta \hat{\mathbf{B}}$  quantity for a plane-segment pgg-2 direction thus has two eigenstates  $\mathbf{B}^+ = +\beta \mathbf{i}$  or  $\mathbf{B}^- = -\beta \mathbf{i}$  and the quantitative eigenvalues  $+\beta$  and  $-\beta$  for each area. When you have an area, you should seriously consider its orientation and which of the two bivectors **B** or  $-\mathbf{B}$  you use for intuition.

# 5.2.6.2. The Hodge Coordinate for the Pseudoscalar Span in the P plane Concept

All bivector pseudoscalars in the plane  $\mathfrak{P}$  idea are proportional to the basic unit bivector

$$(5.76) \qquad \mathbf{B} = \beta \mathbf{i}$$

For all  $\forall \beta \in \mathbb{R}$  we have the Hodge<sup>224</sup> map:  $\beta \to (*\beta) = \mathbf{B} = \beta \mathbf{i}$  for the plane idea. This is a linear one-to-one map from the real numbers to the pseudoscalars of the *directional* primary quality of second grade (pqg-2) for the P plane concept. These pseudoscalars represent the *directional* area *quantity* of a plane, where the negative parameter coordinates  $\beta < 0$  represent the retrograde area opposite orientated to a progressive area  $\beta > 0$ . ( $\beta = 0$  represent every *pqg*-0 point in  $\mathfrak{P}$  without any *direction*).

## 5.2.6.3. Operations with the Unit Bivector Pseudoscalar for a Plane The operator $\mathbf{i}$ acts on the space concept $\mathfrak{G}$ and creates one plane *direction*. Implicitly $\mathbf{i} = \mathbf{\sigma}_2 \mathbf{\sigma}_1$ is given by the two orthonormal geometric 1-vector-operators. First $\mathbf{\sigma}_1$ operates in space and sets a linear *direction*, then $\sigma_2$ operates perpendicular to $\sigma_1$ through space and by that spans a plane *direction* through the plane unit segment $\mathbf{i} \coloneqq \mathbf{\sigma}_2 \mathbf{\sigma}_1$ .

 $^{223}$  I am sorry to tell you that this book uses the reversed order of that first defined by David Hestenes in [6] and [5] (11). It is essential for the intuition in this book that we use the sequential left operational order in vector multiplication like function operation  $f \circ g = f(g) = fg$ . Then the unit pseudoscalar bivector for the plane is  $|\mathbf{i} \equiv \sigma_2 \sigma_1|$ <sup>224</sup> The idea to call this a Hodge map of the form  $\beta \to *\beta$  is taken from reference [35]

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